

DEPARTMENT OF TRANSPORTATION



COAST GUARD

EXPERIMENTS



IN

SMALL CRAFT LEEWAY

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U.S. Coast Guard Oceanographic Unit Washington, D. C.

Oceanographic Unit Technical Report 77-2

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EXPERIMENTS IN SMALL CRAFT LEEWAY

By

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ABSTRACT

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EXPERIMENTS IN SMALL CRAFT LEEWAY

INTRODUCTION

Leeway as described in the National Search and Rescue (SAR) Manual, CG-308, is the effect of wind on a drifting craft. There has long been an interest in providing better data for the computation of leeway in search planning. Early efforts in this area include the work of Woods Hole Oceanographic Institute (Pingree, 1944) on life raft leeway during World War II (fig. 1), and experiments conducted by Chapline (1959) in Hawaii (Table 1). The SAR Manual, however, only presents leeway curves for life rafts. More complete curves of leeway were recognized as a development which could improve search planning. Accordingly, in 1967 the Coast Guard Oceanographic Unit undertook to develop and conduct controlled experiments to measure small craft leeway. The persons most directly concerned with planning and carrying out these experiments include J. H. Seabrooke (1967 - 1968), R. C. Clasby (1967 - 1968), A. W. Garcia (1969 - 1970), H. B. Gehring (1970), R. Still (1970 - 1971), R. C. Murrell (1970 - 1971). These experiments began in January 1968 with the first Search and Rescue Research (SARR) cruise. A total of three cruises were made that year. The result of these cruises established guidelines to follow for future cruises. In June 1969 Barbados Oceanographic and Meteorological Experiment (BOMEX) successfully utilized the established methods to obtain many hours of drift data on the 7-man life raft. Valuable data on a variety of drift objects were Collected during a series of cruises during the period January 1970 to March 1971. The primary purposes of this report are to present the data collected on these cruises and to present a preliminary analysis, based on the January 1970 to March 1971 data, of the relationship between leeway and wind speed for various small craft. In 1975 this preliminary analysis,

and similar work by the Coast Guard R&D Center, Groton, Conn. (Hufford and Broida, 1974) revealed that the tables found in CG 308 are suspect at moderate to high wind velocities, and confirmed that various types of survival craft have different leeway characteristics.

DATA COLLECTION

Since leeway is the motion of a floating object relative to the water, a particularly simple and effective way to collect leeway data is to track the trajectories of drifting craft relative to a surface current drogue.

Additionally, tracking the current drogue relative to a fixed target or navigational fixes of the research vessel will yield information on the surface current. The drifting craft and surface current drogue used in these experiments are illustrated in figures 2 through 6. The drift objects were tracked by recording the ranges and bearings of the drift objects and the current drogue. Range was measured by the ship's radar; bearing was measured visually (preferably) or by radar. Wind speed and direction were measured by the vessel's anemometer or a Bendix Frieze wind speed sensor. Data was collected normally every 20 minutes, although the period sometimes varied from this. Ship's speed and course were recorded from the engineering log and the gyro compass respectively.

Model SST-119XA radar transponders manufactured by Motorola Inc. of Scottsdale, Arizona were installed on the drift objects and current drogue. The power pack consisted of two 12-volt DC lead acid batteries connected in series and attached to the transponder by Marsh and Marine connectors. To provide visual identification in the dark, each object was fitted with a distinctive xenon flashing light, model 300-100R, manufactured by Guest Corp., W. Harford, Conn. The drifting craft were generally weighted with surplus anchor chain to simulate occupancy and missing machinery.

DATA REPORT

General information on all the cruises carried out under this project are shown in Table 2. Appendix 1 contains all the raw data collected on these cruises. These forms are basically self-explanatory, but for complete clarification, the columns are explained at the beginning of Appendix 1. The data are also on file at the Coast Guard Oceanographic Unit in the form of computer cards in a similar format as Appendix 1.

PRELIMINARY LEEWAY VS. WIND SPEED GRAPH

With the objective of preparing a preliminary leeway vs. wind speed graph for use in SAR, the data from five cruises were reduced as described below.

First, leeway speed was computed trigonometrically from the change in displacement of the small craft relative to the surface current drogue during the observation period; then the observed leeway and the observed wind were used to compute leeway speed as a percent of wind speed.

Finally, for each type of small craft, the observations were sorted into intervals centered on 2.5, 7.5, 12.5, 17.5, 22.5, and 27.5 knots, and the average leeway percent was found for each interval. The speed of leeway was then plotted against the wind speed in knots to attain the leeway of each type of small craft within the intervals, producing a series of graph segments (figure 7) which were then smoothed (figure 8) to produce the preliminary graph (figure 9).

Figure 9 also shows the results of similar experiments conducted by the Coast Guard Research and Development Center (Hufford and Broida, 1974). The general agreement between the two sets of results, particularly for winds above 18 knots, is fairly good. The apparent relatively high leeway associated with low wind speeds might be an artificiality resulting from leeway speed data scatter remaining above a threshold value even when wind speed becomes quite low.

REFERENCES

- Chapline, W. E. (1959) Estimating the Drift of Distressed Small Craft.
 Coast Guard Alumni Association Bulletin, USCG Academy, New London, CT.
 p. 39-42.
- Hufford, G. L. and S. Broida (1974). Determination of Small Craft Leeway. CGR&DC Technical Report 39/74. U.S. Coast Guard.
- Pingree, F. deW., (1944) Forethoughts on Rubber Rafts, Woods Hole Oceanographic Institution. 26 pp.

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TABLE 1
LEEWAY RATES (ADAPTED FROM CHAPLINE (1959))

TYPE OF BOAT	LEEWAY	AS	PERCENT	OF	WIND
Surfboards			2%		
Heavy displacement, deep draft sailing vessels			3%		
Moderate displacement, moderate draft sailing vessels and fishing vessels such as trawlers, trollers sampans, draggers, seiners, tuna boats, halibut boats, etc.			4%		
Moderate displacement cruisers			5%		
Light displacement cruisers, outboards, planing hull types,					
skiffs, etc.			6%		

TABLE 2 - SARR CRUISES

				DRIFT	
CRUISE	VESSEL	DATES	LOCATION	OBJECTS	RESULTS
SAR Research #1	USCGC EVERGREEN	4-12 JAN 1968	Vicinity Nantucket Lightship	X Liferafts intended but heavy weather prevented deployment	38 hr of drogue observations
SAR 9/68 Research #2	USCGC EVERGREEN	19-23 SEPT 1968	Vicinity Nantucket Lightship	X 7 20	10 hr tracking drift objects
SAR 10/68 Research #3	USCGC EVERGREEN	21-25 OCT 1968	Cape Cod Bay	X 7 20	v12 hr tracking drift objects
BOMEXC	USCGC COURAGEOUS	22-29 JUNE 1969	17° 35'N 54° 35'W BOMEX STATION BRAVO	X 7	160 hrs (83 hrs use- able)
BOMEXL	USCGC LAUREL	11-15 JULY 1969	15° 23'N 56° 35'W BOMEX STATION BRAVO	X 7	83 hrs
ROSARR 1-70	USCGC ROCKAWAY	15-18 JAN 1970	35N 72W 100 mi east of Cape Hatteras	X 7 16	169 sampling periods of 20 minutes each
ROSARR 5-70	USCGC ROCKAWAY	5-10 MAY 1970	Argus Island Tower 22 mi SSW of Bermuda	X 7 16	206 sampling periods of 20 minutes each
EVSARR 9-70	USCGC EVERGREEN	11-25 SEP 1970	37N 71W 125 mi east of Cape Hatteras	X 7 16 18	1539 sampling periods of 20 minutes each
EVSARR 12-70	USCGC EVERGREEN	4-12 DEC 1970	Argus Island Tower 22 mi SSW of Bermuda	X 7 16 18 30	394 sampling periods of 20 minutes each
EVSARR 2-71	USCGC EVERGREEN	25 FEB - 4 MAR 1971	Argus Island Tower 22 mi SSW of Bermuda	X 7 16 18 30	939 sampling periods of 20 minutes each

Drift Objects:

X - Surface Current drogue

1 - One man life raft

7 - Seven man life raft

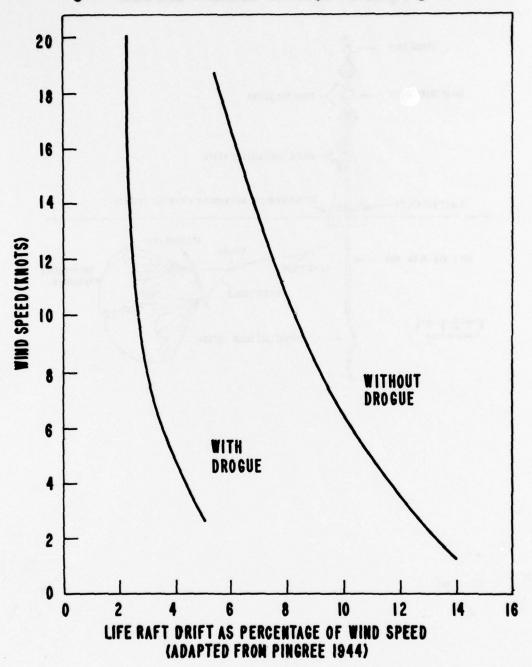
16 - Sixteen foot plastic boat hull 18 - Eighteen foot plastic boat hull 20 - Twenty man life raft

30 - Thirty foot wooden boat

Table 2 (continued)

The drift craft in all cases, except for the rafts, are presumed not to have been attached to a sea anchor. For the rafts, on 5 of 8 cruises there is a definite statement that the rafts were attached to sea anchors; on the other 3 cruises there is no definite statement. It is presumed that the rafts were attached to sea anchors in all cases.

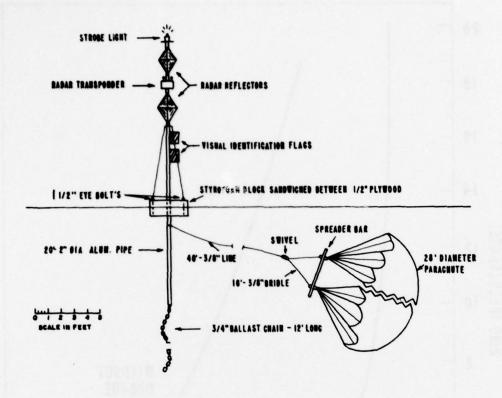
Figure 1—LIFE RAFT LEEWAY (adapted from Pingree, 1944).



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Figure 2-SURFACE CURRENT DROGUE.



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Figure 3-MARK-7 INFLATABLE LIFE RAFT.

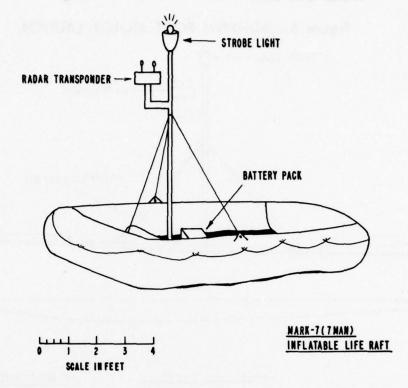
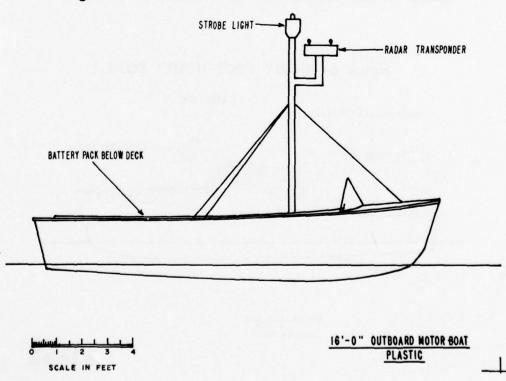


Figure 4—SIXTEEN FOOT OUTBOARD MOTOR BOAT.



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Figure 5-EIGHTEEN FOOT MOTOR LAUNCH.

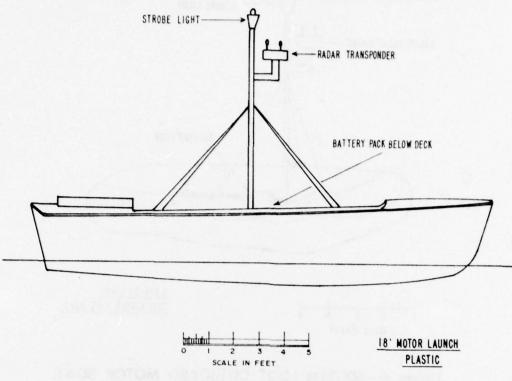
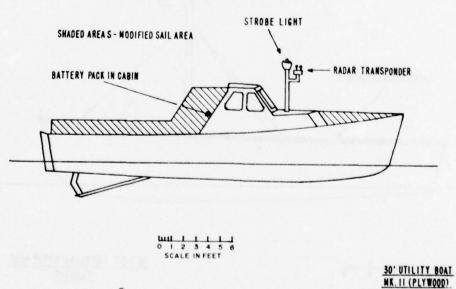
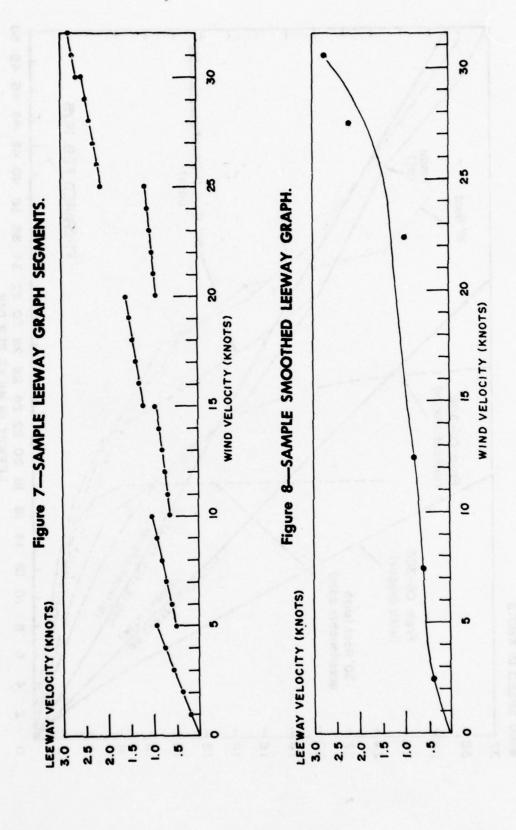


Figure 6—THIRTY FOOT UTILITY BOAT.





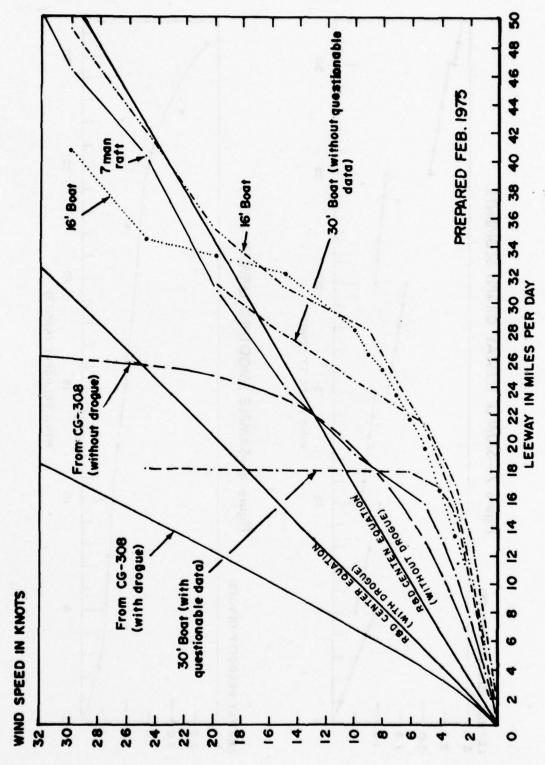


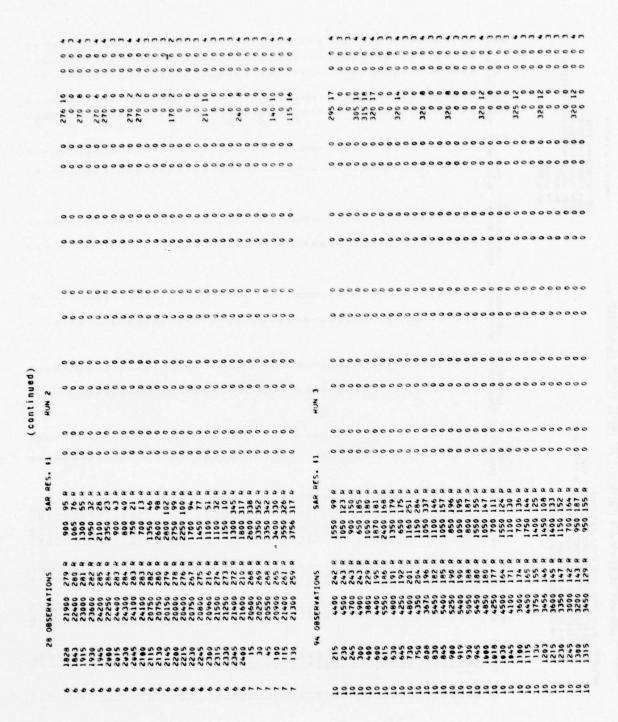
Fig. 9 Preliminary Leeway vs Wind Speed

Appendix 1

This appendix contains a listing of the observational data used in technical report.

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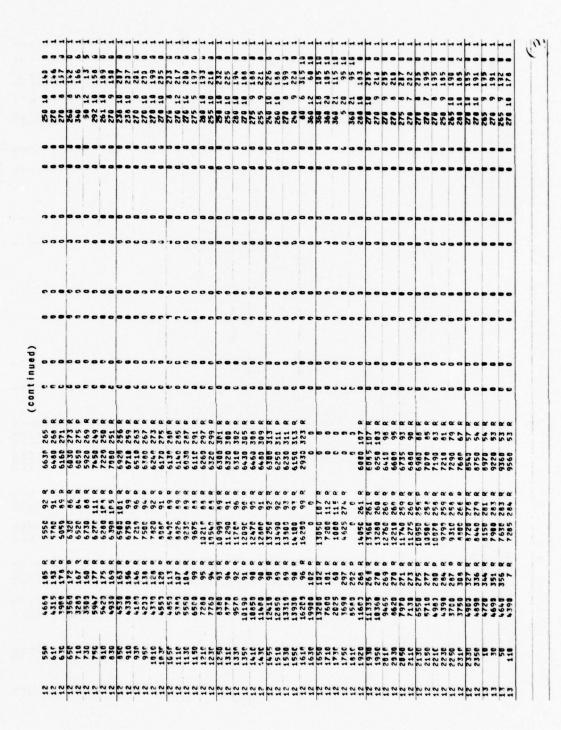
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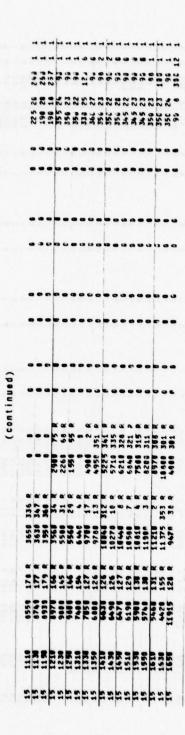
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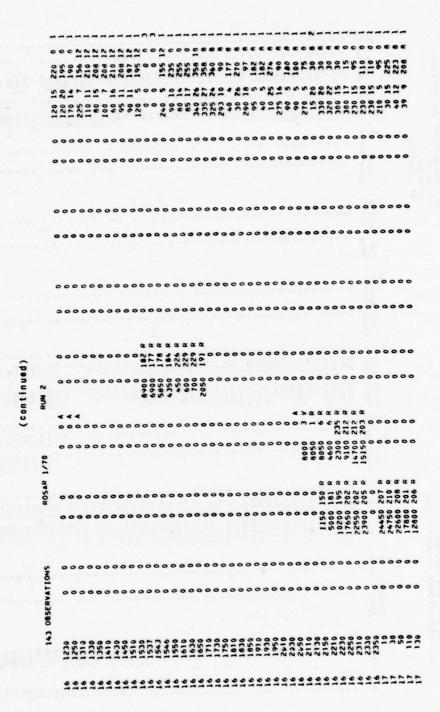


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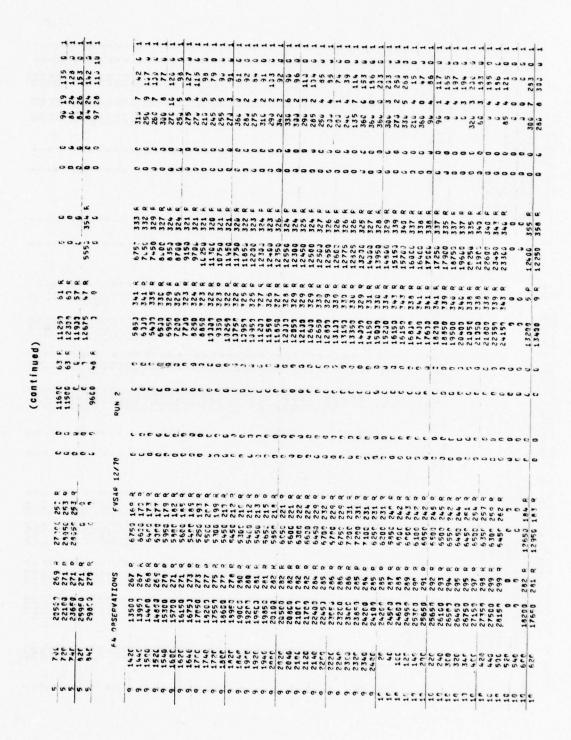
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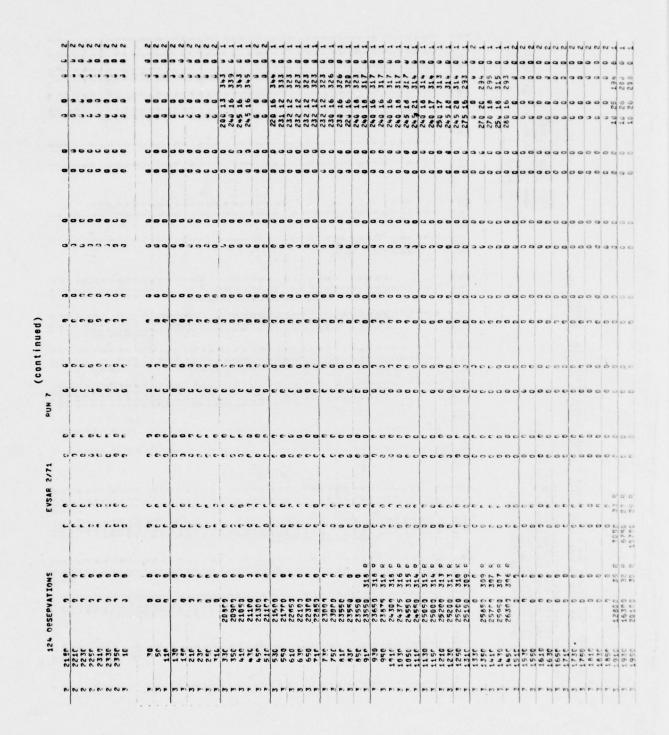
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	18FT	3650	3650	3930	3930	3400	3617	3350	2950	2910	2937	2913	2450	2359	1850	1775	1725	1639	1775	1830	6 900	13575	13625	10367	2.830	15739	6	9433	4750	6953	
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APPENDIX 2

A program description with abbreviated documentation and a program listing with typical outputs are found in this appendix. All computations were done using PROGRAM RAFTL.

Name: RAFTL

Programmer: CDR C. W. MORGAN

Originator: CDR C. W. MORGAN

Date: 8 June 1977

<u>Purpose</u>: The function of this program is to aid the oceanographer/engineer in evaluating the quality of leeway angle and leeway factor observations.

Machine: CDC 3300

Source Language: FORTRAN

<u>Description</u>: Leeway is the movement of a drifting object relative to the water. Leeway angle is the angle between wind direction (toward) and leeway direction. Leeway factor is the ratio of leeway speed to wind speed. Program RAFTL exists to compute true wind speed and direction, leeway angle, and leeway factor from sequential observations of time, range and true bearing a current drogue, range and true bearing of a drift object, ships course and speed, and relative wind direction and speed. The program outputs line printer graphs of geographic displacement of the drift object relative to the drogue, leeway angle vs time, leeway factor vs time, leeway angle vs wind speed, and leeway factor vs wind speed.

The program basically proceeds as follows:

- 1. Read in data for each observation
- Computes the true wind from the ships course and speed and relative wind direction and speed.
- 3. Computes the distance between the drogue and drift object using their ranges and bearings.
- 4. Computes leeway direction and speed from the change in position of the raft relative to the drogue during a 6 hour interval.
- 5. Computes the average vector wind direction and speed during a 6 hour interval.
 - 6. Computes leeway angle.
 - 7. Prints out and punches cards for:
 - a. Time at the beginning of the 6 hour interval

- b. Average vector wind direction (toward) and speed (knots) during the interval.
 - c. Leeway direction and speed (knots) during the interval.
 - d. Leeway angle (+ to right, to left) and factor.
 - 8. Prints out individual observation data
 - a. Observation time
 - b. X and Y component of true wind
 - c. X and Y components of distance from drogue to drift object.
 - d. Drogue range and bearing
 - e. Drift object range and bearing
 - f. Relative wind direction (from) and speed
 - g. Ship heading and speed
- 9. Computes the counter of the observations on which plotting symbols are to change.
 - 10. Calls plot subroutine for line printer plots.

All calculations are based on elementary kinematics and trigonometry.

USAGE: The program deck is set up as follows:

\$JOB, 42483, RAFTL-SE, 2, 2000, 500 \$SCHED, CORE=40, TIME=1, CLASS=C \$MAP=N \$FTNU(X)

Program	RAFTL
Subroutine	CARTM
Subroutine	CIRCM
Subroutine	PLOTA

FINIS

\$OBJ,LGO

Observations in interval card, INTV. (This card gives the number of observational intervals in the 6 hour interval e.g. for 15 minute observations INTV=24, for 20 minute observations INTV=18.)

Data Identifier Card (40 column free (A) format.)

Input Data Cards

Col	Data
3-6	Time (hours and minutes)
16-20	Range to drogue (YARDS)
21-23	Bearing to drogue (°T)
25-29	Range to drift object (YARDS)
30-32	Bearing to drift object (°T)
70–72	Relative wind direction (°R) relative to ships head
73-74	Relative wind speed (knots)
75-77	Ship's head (°T)
78-79	Ship's speed (knots)

9999 card in columns 3-6 Continuation card (in columns 1 and 2; use 01 if more runs follow, use 02 if last run)

Additional sets of Data Identification Cardy Input Data Cards, and 9999 card, and Continuation Card as required

88

RESTRICTIONS:

- 1) RAFTL was designed for an analysis interval of 6 hours.
- 2) Relative wind must be in degrees relative to ships head. If the relative wind is in °T, then line 26 must be changed to AG = RWD(I).
- 3) The input format for drift object range and bearing was specifically designed for the data cards for SARR cruises to read the 7 man raft data. Since these cards also contain data on other drift objects the input format can be easily changed to accommodate them.
- 4) RAFTL was designed to handle range and bearing inputs in yards and °T.
- 5) There must be exactly INTV observations intervals per 6 hour interval. If wind data is missing it must be estimated or the program invalidly assumes calm conditions.
- 6) If drogue and/or drift object data is missing insert 999 in the input bearing field of either. This will cause outputs of 99999. in drogue to drift object X coordinate, in leeway direction, leeway speed, leeway angle, and leeway factor. Later, in PLOTA a value of 99999. in either X or Y array will cause that X, Y pair to be skipped in the plotting subroutine.
- 7) RAFTL is set up to change plotting symbol after every tenth data point.
 - 8) The program is free standing.

Storage requirements: See attached MAP.

Subroutines required: PLOTA

CARTM

CIRCM

Operational Environment:

Device	Function	Special Requirements
Card reader	input	none
Line printer	output	none
Card punch	output	none

Operational characteristics: See Description.

Errors and Diagnostics: None used

References: For more on application of program see report by C. W. Morgan on "Observations of Leeway Angle and Leeway Factor for 7 Man Rafts."

Name: Subroutine CIRCM

Programmer: D. D. Frydenlund, Modified by C. W. Morgan

Originator: D. D. Frydenlund

Date: 8 June 1977

Purpose: To convert from rectangular to geographic polar coordinates

Machine: CDC 3300

Source Language: FORTRAN

Description: This subroutine simply converts from rectangular coordinates

(X positive east; U positive north) to geographical polar

coordinates (0° - 360°, clockwise, 0° = north).

USAGE: CIRCM (XI, YI, BRGI, DISI)

XI Rectangular coordinate positive to east

YI Rectangular coordinate positive to north

BRGI Geographical polar coordinate for angle

DISI Geographical polar coordinate for distance

Restrictions: None

Storage Requirements: See Map attached to program RAFTL

Subroutines Required: None

Operational Environment: Not applicable

Operational Characteristics: See Description

Errors and Diagnostics: None

References: None

NAME: Subroutine CARTM

Programmer: D. D. Frydenlund, Modified by C. W. Morgan

Originator: D. D. Frydenlund

Date: 8 June 1977

Purpose: To convert from polar geographic coordinates to rectangular

coordinates.

Machine: CDC 3300

Source Language: FORTRAN

Description: This subroutine simply converts from geographical polar coordinate (0° - 360°, clockwise, 0° - north) to rectangular coordinates (X positive east; Y positive north) using elementary trignometry.

USAGE:

CARTM (ANG, DIST, X, Y)

ANG Geographical polar coordinate for angle

DIST Geographical polar coordinate for distance

X Rectangular coordinate positive to east

Y Rectangular coordinate positive to north

Restrictions: None

Storage Requirements: See Map attached to program RAFTL

Subroutines Required: None

Operational Environment: Not applicable

Operational Characteristics: See Description

Errors and Diagnostics: None

References: None

NAME: Subroutine PLOTA

Programmer: J. H. Discenza, Modified by C. W. Morgan

Originator: J. H. Discenza

Date: 8 June 1977

Purpose: The purpose of this subroutine is to plot an array of X data vs

an array of Y data on the line printer.

Machine: CDC 3300

Source Language: FORTRAN

Description: Subroutine PLOTA basically functions as follows:

1) Finds boundary values for the X and Y arrays.

- 2) If the X and Y scales are to be unequal, they are simply scaled by the numbers of spaces in the X and U plot fields, 100 and 54 respectively
- 3) If the X and Y scales are to be equal, the appropriate scaling is carried out (lines 33 42).
 - 4) X-Axis labeling array is generated.
- 5) Each of the 55 lines in the interior of the plot is then generated and printed. Before the first line and after the last line, labels and axes are printed. In generating each line of print, all spaces are set blank, then the data points falling within the Y interval of the line are sorted out and the appropriate plotting symbol replaces the blank at each X interval within which an X value falls. Twenty six plot symbols are available. The appropriate plot symbol is assigned during the Y-sort.

USAGE:

IOP

PLOTA (XRAY, YRAY, NOPTS, NOPER, IOP)

XRAY The array of X values

YRAY The array of Y values

NOPTS Number of points in X or Y array

NOPER Array of successive, cumulative, cutoff points in data array after which a character change is desired in the plot. The value of the last NOPER should equal NOPTS

An option for the equality of the plotting axes. IOP=1 will give a plot in which I unit length on the X axis equals I unit length on the Y axis. IOP=2 will scale the axes so that the plot fills both axes.

Restrictions: None

Storage Requirements: See Map attached to program RAFTL

Subroutines Required: None

Operational Environment: Not applicable

Operational Characteristics: See Description

Errors and Diagnostics: None

References: None

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06/10/77 PROGRAM RATL
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PARE 003

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USASI FORTRAN DIAGNOSTIC RESULTS FOR RAFTL

ERRORS

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N

PAGE 002

USASI FORTRAN DIAGNOSTIC RESULTS FOR PLOTA

ERRORS

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10-10-1

SUBROUTINE CIRCH (XI,YI,BRGI,DISI)

SUBROUTINE

F(YI,E2.0.) GO TO \$5.2958

SCONTINUE

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IF (XI) 10-20.30

USASI FORTRAN DIAGNOSTIC RESULTS FOR CIRCH

NO ERRORS

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GO TO ***

ANKEANG-10.

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AG CONTINUE
RETURN
END ANSI FORTRAN(2.3) /HASTER

PASE 001

USASI FORTHAN DIAGNOSTIC RESULTS FOR CARTH

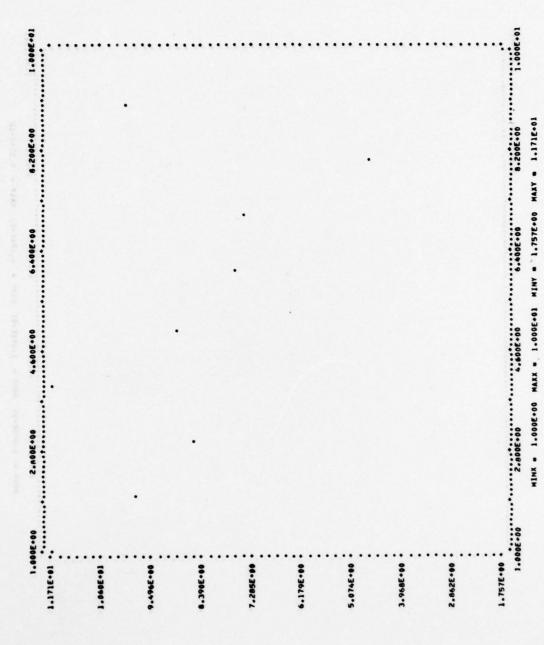
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II-17

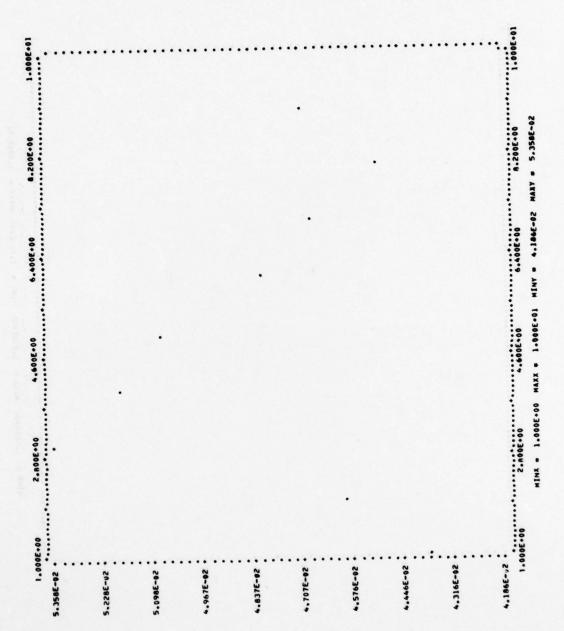
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Q.KONVRI UFATAN Q.BOUT RAFTL					150051	CIRCH	ERR.2	EXPOUT.	IEXFLT	L062	NUMIOERR	PLOTA	O. ARGHAD	O. BARGAD	O.CAL ADR	D.DBSHFT	150.0	O-EOACON	O.EXP2		1000	1000	D.NIISAST	0.078004	O.SAVAS	0.50UT	O.TYPE	090SLECT	SIMACC.1	OIC
\$3230 \$1035 67434					56370	65631	57463	62676	53732	53006	60370	66401	52175	50374	55460	57235	57156	24641	22925	25115	0000	2000	72663	62100	50345	62021	57357	53622	50357	72370
G.EXAR UFIDUTIL PLOTA					ATANS	CARTH	ERR.15	EXPFLAG	IDVCHK	LASTCHR.	NUMBER . 2	000M-	O. ARGADA	O. BCDOSP	Q.BUFSWX	O.CZDATA	1000.0	0.58001	O.EXPFLG		יות ביים	TONOS.	0.NO	0.0TBCD2	O.RTNAME	O.SINP	O.SWTCHX	OSORE MND	SIMACC.0	TRNSFER.
53140 53140 57204 66033					42113	65412	57514	54007	53778	63344	63520	21606	50351	53326	56376	503\$2	61035	62140	24007	2110	201101	50737	55272	62073	57153	63554	56375	55745	50386	63466
UFUTICALOG					MATA	CANEXPOV	ERR.1	Exp.	TARFLT	INTZERO.	NUMBER .	P.EXRR	0.AL06	O. BCDIAN	O.BUFPNT	0.00	0.00UBAD	O.EBCIN	0.EXP	2000		at ANON	D.NHOT	0.078001	O.REWND	O.SIN	9.STORE	090E0F	SELEXPOV	STR.XIT
186313 52731 54247 65631					53310	54030	57461	52712	53670	63303	63516	23140	53122	63620	60732	52477	51113	63676	53701	20000	63637	20700	62351	62046	55745	52211	63457	56106	24015	63462
8666144006/186343 UFEXP 52731 Q-ERFOR 54247 CARTH 65631	-				A1 06	CANDVELT	DE.00T	EXP	GETSIGN.	INPABT	MODUTABI	0000	O. ADDRES	0.00001	O.BUFFER	0.CONDS1	0.017100	D.DEIDTH	O.ERROR		INDICE	O.KONVDI	0.MUL TDD	0.007800	O.PNTP	0.SETT0	0.STOP	0908KSP	SELDVFLT	NIS
50274 52547 54067 65412	0445' moo	COMM CHE	DATACHE	DATACHE	ENTR STIZE AL	54025	62670	52712	63453	65346	63511	11115	20446	57155	56711	55232	25005	57355	24097	43544	61412	50721	51614	54036	57160	20447	53505	26010	54011	52211

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											240.	240.	240.	240.	250.	280.	245.	243.	243.	250.	260.	272.	276.	281.	291.	278.	283.	565.	280.	278.	283.	280.	281.	285.	305.	305.	55.	55.
												3.	3	3.	3	3.	3.	3.	3.	:	:	:	:	•	•	•		•	•		•	•	7.	10.	10.	•	3.	2.
											290.	290.	290.	290.	200.	280.	285.	205.	285.	285.	205.	285.	280.	290.	280.	280.	285.	290.	280.	270.	280.	285.	285.	295.	200.	285.	90.	70.
											178.	176.	175.	174.	172.	172.	172.	172.	170.	167.	167.	166.	164.	159.	161.	156.	155.	155.	149.	148.	145.	143.	142.	143.	143.	145.	155.	203.
	\$015g	940	950	052	150	840	047	540	140	240	4450.	4350.	4250.	4100.	3900.	3650.	3500.	3450.	3350.	3350.	3350.	3350.	3350.	3450.	3300	3350.	3350.	3250.	3250.	3400.	3350.	3700.	3900.	4100.	***	4800.	5250.	9400
	0			•	•	•	•	•	•	•	. 761	195.	193.	193.	192.	.261	193.	193.	191.	191.	192.	191.	.661	187.	.60	.66	.88	.06	.88	.68	188	188.	196.	185.	.56	. 94.	.06	.00
	ANGLE	9.6	8.6	11.7	6.9	7.7	7.5	4.7	10.1	1.8	5350.	5350.	5000.	5000.	.0064	4900.	4850.	*0067	4850.	4800.	.0064	5150.	5250.	5350.	4750.	5950.	.0009	6100.	6050	6550.	6850. 1	7150.	7500.	7900.	8250. 1	8800.	.0066	5400. 2
	TO/KTS)																																		4705.			
	LEEWAYLT	25	22	27	25	52	27	27	35	88	1450.	1688.	1495.	1553.	1562.	1527.	1578.	1582.	1507.	1669.	1772.	1793.	1745.	1988.	1817.	2293.	2251.	2433.	2516.	2826.	2875.	3222.	3185.	3156.	3367.	3367.	3938.	3557.
200	KTS)	5.3	9.5	5.9	6.2	6.5	6.8	::	7.5	7.8																												
0//6	10151W	13.	13.	15.	16.	18.	20.	22.	54.	27.	2.95	2.95	2.95	2.95	2.95	2.82	2.95	2.93	2.93	5.98	5.98	5.74	5.17	98.9	98.9	7.61	4.06	7.73	8.46	7.92	7.36	7.25	67.9	7.66	7.43	5.14	8.19	6.88
SAKE	-										-0.52	-0.52	-0.52	-0.52	-0.52	1.63	-0.52	-0.62	-0.62	-0.52	0.52	1.75	1.65	4.12	4.12	2.47	3.76	2.07	3.08	=	3.13	3.38	3.07	6.43	69.9	6.13	6.47	6.55
ZB EVSAR	2136	2150	2210	2230	2300	2320	5340	0	50	04	2130	2150	2210	2230	5300	320	340	•	50	0,	100	150	140	500	550	540	300	350	340	000	450	044	200	250	240	900	620	340

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Cuttors Control



STORY STATE

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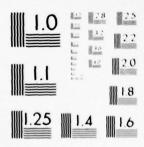
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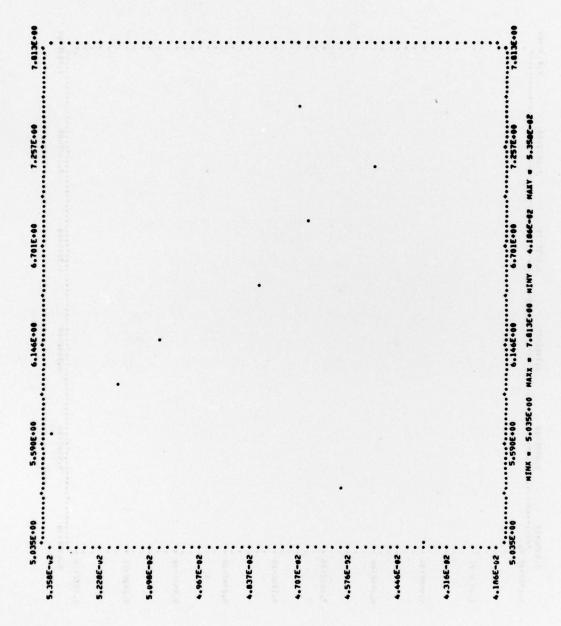
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